Teledyne RD Instruments

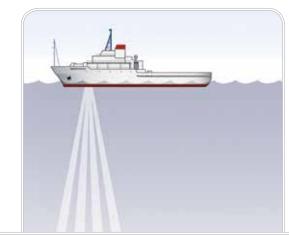
Ocean Surveyor

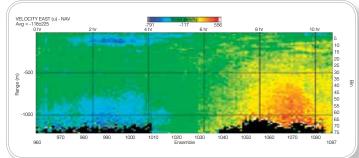
Vessel-Mount Long Range 3-D Current Profiling

Explore New Depths with Proven ADCP Technology

For over thirty years, Teledyne RD Instruments has been the preeminent supplier of Acoustic Doppler Current Profiling (ADCP) instrumentation for open ocean applications. Teledyne RDI's vessel-mounted OCEAN SURVEYOR family of ADCPs are the only instruments capable of collecting detailed maps of the distribution of water currents and suspended materials through the water column and along the ship's path—at depths and resolutions previously considered unattainable. In real time, the ADCP is also used to aid in situ decision-making, to adapt field operations, and to understand current regime characteristics.

Frequency	Range (m)	Cell Size (m)		
38kHz	>1000	24		
75kHz	>700	16		
150kHz	>400	8		





PRODUCT FEATURES

- Versatile: Broadband signal processing combines with Narrowband processing to provide the ultimate in data versatility.
- Compact: Patented phased array transducers significantly reduce the transducer size and weight for ease of installation.
- Comprehensive: The Ocean Surveyor combines current profiling, backscatter profiling, and Doppler Velocity Log capability all within a single instrument.
- **Four-beam solution:** Patented phased array 4-beam design provides increased data reliability and quality assurance.

Applications:

- Climate studies
- · Mid-ocean frontal mapping
- Fisheries research
- Deep-water cable-laying projects





Ocean Surveyor

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TECHNICAL SPECIFICATIONS

Water Profiling	Long Range Mode	38kHz		75kHz		150kHz			
	Vertical resolution cell size ¹	Max Range ²	Precision ³	Max Range ²	Precision ³	Max Range ²	Precision ³		
	4					>350m	30cm/s		
	8 16	>1000m	70cm/c	>650m >700m	30cm/s	>400m	16cm/s		
	24	>1000m	30cm/s 20cm/s	>/00111	16cm/s				
	High Precision Mode	38kHz		75kHz		150kHz			
	Vertical resolution cell size ¹	Max Range ²	Precision ³	Max Range ²	Precision ³	Max Range ²	Precision ³		
	4					>225m	15cm/s		
	8	. 000	1 F /-	<425m	15cm/s	>250m	8cm/s		
	16 24	>900m >950m	15cm/s 10cm/s	>450m	7cm/s				
Profile Parameters	Velocity accuracy (typical) ±1.0% ± 0.5cm/s		cm/s	±1.0% ± 0.5cm/s		±1.0% ± 0.5cm/s			
	Velocity range -5 to 9m/s			-5 to 9m/s		-5 to 9m/s			
	Number of depth cells Maximum ping rate	1-128 0.4Hz		1-128 0.7Hz		1-128 1.5Hz			
Bottom Track	Max altitude (precision <2cm/s) Range Accuracy = <±2% actual		950m			540m			
Echo Intensity Profile	Vertical resolution Depth cell size, user configurable								
	Dynamic range Precision		80dB ±1.5dB						
Transducer and Hardware	Beam angle		30°						
	Configuration Communications		4-beam, phased array RS-232 or RS-422 hex-ASCII or binary output at 1200–115,200 baud						
					or binary output	. at 1200-115,200	Dauu		
System Power	AC input Power		90-250V 1400W	AC, 47–63Hz					
Software	Use TRDI's Windows™-based software for best results:								
	VMDAS — Vessel-Mount Data A	cquisition Sys	tem; WinADCP –	Data Display and E	xport				
Options	Velocity for advanced post processing								
Environmental	Operating temperature Storage temperature			-5° to 45°C -30° to 60°C					
Standard Sensors	Temperature (mounted on transducer)		Range -5°	Range -5° to 45°C, Precision ±0.1°C, Resolution 0.03°					
System Components	 38,75, or 150kHz transducer 19" rack-mount electronic chassis All-purpose deck box 								
	Gyrocompass interface board								
	 LCD gyro offset control display User to supply compass input or GPS navigation data and NMEA tilt information 								
	,								
Dimensions	38kHz: 914.4mm dia.; 75kHz: 480mm dia.; 150kHz: 305mm dia. (line drawings available upon request)								

- 1 Ranges at 1 to 5 knots ship speed are typical and vary with situation.
- 2 Single-ping standard deviation.
- 3 User's choice of depth cell size is not limited to the typical values specified.
- 4 Excludes errors introduced by changes in speed of sound profile, by tilting of transducer, and by slope of bottom.
- 5 Up to ±20° tilt.



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